

# Manifolds

## 1. Exercise Sheet



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### Groupwork

#### Exercise G1 (Euclidean topology on $\mathbb{R}^n$ )

Consider  $\mathbb{R}^n$  with the Euclidean topology  $\mathcal{O}_E$ . That is the topology induced by the Euclidean metric:

$$U \subseteq \mathbb{R}^n \text{ open} \quad :\iff \quad \forall x \in U \exists \varepsilon > 0 : B_\varepsilon(x) \subseteq U.$$

- Show that  $\mathcal{O}_E$  is a topology on  $\mathbb{R}^n$ .
- Show that  $(\mathbb{R}, \mathcal{O}_E)$  is Hausdorff.
- Show that  $(\mathbb{R}, \mathcal{O}_E)$  is second-countable.

#### Hints for solution:

- The condition obviously holds for the empty set and the whole space. Hence,  $\emptyset, \mathbb{R}^2 \in \mathcal{O}_E$ .  
Let  $(U_i)_{i \in I}$  be a family of open set and  $V$  their union. Then for  $x \in V$  there exists an  $i_0 \in I$  such that  $x \in U_{i_0}$ . Then there exists an  $\varepsilon_{i_0} > 0$  such that  $B_{\varepsilon_{i_0}}(x) \subseteq U_{i_0} \subseteq V$ . Thus,  $V$  is open.  
Now suppose that  $I$  is finite, and let  $W$  be the intersection of the  $U_i$ . If  $x \in W$ , then  $x \in U_i$  and there are  $\varepsilon_i > 0$  such that  $B_{\varepsilon_i}(x) \subseteq U_i$  for all  $i \in I$ . Then for  $\varepsilon := \min \varepsilon_i$  we have  $B_\varepsilon(x) \subseteq W$  and  $W$  is open.
- Let be  $x, y \in \mathbb{R}^n$ . Then for  $\varepsilon := \frac{1}{3} \|x - y\|$  the open sets  $B_\varepsilon(x)$  and  $B_\varepsilon(y)$  are disjoint.
- The balls with rational midpoint and rational radii are a countable base.

#### Exercise G2 (Topological Manifolds)

Let  $M_1$  and  $M_2$  be topological manifolds. Discuss without proof whether the following sets are topological manifolds. Consider the sets in d) to f) as subsets of  $\mathbb{R}^2$  with the Euclidean topology  $\mathcal{O}_E$ .

- |                       |                          |   |
|-----------------------|--------------------------|---|
| a) $M_1 \cap M_2$ ,   | d) $\{x^2 + y^2 = 1\}$ , | g) $(\mathbb{R}^n, \mathcal{O}_E)$ ,  |
| b) $M_1 \cup M_2$ ,   | e) $\{x^2 - y^2 = 1\}$ , | h) $(\mathbb{R}^n, \mathcal{O}_1)$ for $\mathcal{O}_1 := \{\text{all subsets of } \mathbb{R}^n\}$ , |
| c) $M_1 \times M_2$ , | f) $\{x^2 - y^2 = 0\}$ , | i) $(\mathbb{R}^n, \mathcal{O}_2)$ for $\mathcal{O}_2 := \{\emptyset, \mathbb{R}^n\}$ .             |

### Hints for solution:

- a) No, dimension can vary.
- b) No.
- c) Yes.
- d) Yes,  $\mathbb{S}^1$  is a topological manifold.
- e) Yes, each sheet of this two-sheeted hyperbola can be regarded a graph over  $(0, \infty)$ .
- f) No, in a neighbourhood of 0 the set does not admit a graph representation.
- g) Yes, see G1.
- h) No, the open sets are not second-countable.
- i) No, not Hausdorff.

### Exercise G3 (Stereographic projection)

Let  $\mathbb{S}^n := \{x \in \mathbb{R}^{n+1} : \langle x, x \rangle = 1\}$  be the  $n$ -sphere with radius 1 where  $\langle \cdot, \cdot \rangle$  is the standard scalar product on  $\mathbb{R}^{n+1}$ .

- a) Is it possible to construct an atlas on  $\mathbb{S}^n$  with only one chart?

Take the *North pole*  $N := (0, 1) \in \mathbb{S}^1$  and define a map  $x : \mathbb{S}^1 \rightarrow \mathbb{R}^1$  such that  $x(p)$  is the intersection point of the  $x$ -axis with the straight line through  $N$  and  $p$ . This map is called *stereographic projection*.

- b) Construct an atlas with the least number of charts on  $\mathbb{S}^1$  using the stereographic projection.
- c) Generalize this construction to  $\mathbb{S}^n$ .

### Hints for solution:

- a) No, since the chart would be a homeomorphism of the compact space  $\mathbb{S}^n$  onto the non-compact space  $\mathbb{R}^n$ .
- b) see part c).
- c)  $\mathcal{A} = \{(U_+, x_+), (U_-, x_-)\}$  where  $U_{\pm} := \mathbb{S}^n \setminus \{N_{\pm}\}$  with  $N_{\pm} := (0, \dots, 0, \pm 1)$  and  $x_{\pm} : U_{\pm} \rightarrow \mathbb{R}^n$  given by

$$(x_1, \dots, x_{n+1}) \mapsto \left( \frac{x_1}{1 \mp x_{n+1}}, \dots, \frac{x_n}{1 \mp x_{n+1}} \right).$$

The charts are bijective: Indeed,

$$x_{\pm}^{-1} : \mathbb{R}^n \rightarrow U_{\pm}, \quad x_{\pm}^{-1}(u) := \frac{1}{|u|^2 + 1} \left( 2u, \pm(|u|^2 - 1) \right)$$

are inverses to  $x_{\pm}$ . The charts and their inverses are continuous with respect to the relative topology: The coordinate functions are continuous functions, and so is their insertion into

continuous functions. Finally, the two transition maps,  $x_{\pm} \circ x_{\mp}^{-1}$  which map  $x_{\mp}(U_{+} \cap U_{-}) = \mathbb{R}^n \setminus \{0\}$  into itself,

$$\begin{aligned} (x_{\pm} \circ x_{\mp}^{-1})(u) &= x_{\pm} \left( \frac{2u}{|u|^2 + 1}, \mp \left( 1 - \frac{2}{|u|^2 + 1} \right) \right) \\ &= \frac{1}{1 + \left( 1 - \frac{2}{|u|^2 + 1} \right)} \cdot \frac{2u}{|u|^2 + 1} = \frac{1}{2 - \frac{2}{|u|^2 + 1}} \cdot \frac{2u}{|u|^2 + 1} = \frac{u}{|u|^2}, \end{aligned}$$

are differentiable.

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## Homework

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Hand in your solutions until Tuesday, Mai 5<sup>th</sup>.

### Exercise H1 (Alexandroff compactification)

10 points

Let  $n \in \mathbb{N}$  and  $\widehat{\mathbb{R}}^n := \mathbb{R}^n \cup \{\infty\}$ , where  $\infty \notin \mathbb{R}^n$ . Define open sets by

$$\mathcal{O} := \mathcal{O}_E \cup \mathcal{O}_{\infty} := \{U \subset \mathbb{R}^n : U \text{ is open in } \mathbb{R}^n\} \cup \{\widehat{\mathbb{R}}^n \setminus K : K \text{ is compact in } \mathbb{R}^n\}.$$

- Show that  $(\widehat{\mathbb{R}}^n, \mathcal{O})$  is a topological space.
- Prove that  $(\widehat{\mathbb{R}}^n, \mathcal{O})$  is a topological manifold.
- Show that  $\widehat{\mathbb{R}}^n$  is homeomorphic to  $\mathbb{S}^n$ .

### Hints for solution:

- We have  $\emptyset \in \mathcal{O}_E$  and since  $\emptyset$  is compact  $\widehat{\mathbb{R}}^n = \widehat{\mathbb{R}}^n \setminus \emptyset \in \mathcal{O}_{\infty}$ .

Let  $(U_i)_{i \in I}$  be a family of open sets, and let  $V$  be their union. If none of the  $U_i$  contains  $\infty$ , then neither does  $V$ . Hence  $V$  is open in  $\widehat{\mathbb{R}}^n$  since it is open in  $\mathbb{R}^n$ . If at least one of them, say  $U_{i_0}$ , contains  $\infty$ , then let  $K := \mathbb{R}^n \setminus U_{i_0} = \widehat{\mathbb{R}}^n \setminus U_{i_0}$ . Now,

$$\mathbb{R}^n \setminus V = \bigcap_{i \in I} (\mathbb{R}^n \setminus U_i) \subseteq K,$$

so  $\mathbb{R}^n \setminus V$  is closed and contained in  $K$ . Since  $K$  is also closed,  $\mathbb{R}^n \setminus V$  is closed in  $K$  as well. Hence  $\mathbb{R}^n \setminus V$  is compact as closed subsets of compact sets are compact.

Now suppose that  $I$  is finite, and let  $W$  be the intersection of the  $U_i$ . If all of the  $U_i$  contain  $\infty$ , then so does their intersection. Since  $\mathbb{R}^n \setminus W$  is a finite union of compact spaces, it is compact, so  $W$  is open. If one of the  $U_i$  does not contain  $\infty$ , then  $\infty \notin W$ , and we can write  $W$  as a finite intersection of open sets of  $\mathbb{R}^n$ .

- b) Let  $p, q \in \widehat{\mathbb{R}}^n, p \neq q$ . If  $p \neq \infty \neq q$ , we can use two disjoint open sets in  $\mathbb{R}^n$  to separate  $p$  and  $q$ . If one of them is equal to  $\infty$ , say  $q$ , take a closed ball with radius  $r_1$  with center  $p$  and an open ball with radius  $r_2 < r_1$  with center  $p$ . Then, the complement of the closed ball and the open ball are two disjoint open subsets separating  $p$  and  $q$ . Hence,  $\widehat{\mathbb{R}}^n$  is Hausdorff. Second countability is obvious. To show that  $\widehat{\mathbb{R}}^n$  is locally homeomorphic to Euclidean space, construct suitable homeomorphisms (cf. part c)).
- c) Since  $\mathbb{S}^n$  is compact and  $\mathbb{S}^n \setminus \{p\}$  is dense in  $\mathbb{S}^n$ , it suffices to show that  $\mathbb{R}^n$  is homeomorphic to  $\mathbb{S}^n \setminus \{p\}$ . The stereographic projection is the desired homeomorphism. Hence,  $\widehat{\mathbb{R}}^n$  is homeomorphic to  $\mathbb{S}^n$ .

**Exercise H2** (Non-Hausdorff space)

7 points

Let  $L := \{0, 1\} \times \mathbb{R}$ . Define on  $L$  an equivalence relation  $\sim$  by

$$(0, y) \sim (1, y) \iff y \neq 0.$$

- a) What are the equivalence classes on the quotient set  $L / \sim$ ?
- b) Show that  $L / \sim$  is locally Euclidean (locally homeomorphic to  $\mathbb{R}$ ).
- c) Show that  $L / \sim$  is not Hausdorff.

**Hints for solution:** The quotient set  $L / \sim$  is a line with double origin. To show that it is locally homeomorphic to  $\mathbb{R}$  take the projection onto  $\mathbb{R}$ . The quotient  $L / \sim$  is not Hausdorff in the double origin, since for every open neighborhoods of  $(0, 0)$  and  $(1, 0)$  there exists an  $\varepsilon > 0$  such that  $(0, \varepsilon)$  and  $(1, \varepsilon)$  are contained in the neighborhoods, resp., but  $(0, \varepsilon) \sim (1, \varepsilon)$ . Thus, the neighborhoods are not disjoint.

**Exercise H3** (Lie groups)

13 points

A Lie group  $G$  is a topological manifold which is a group such that multiplication  $(g, h) \rightarrow gh$  and inversion  $g \rightarrow g^{-1}$  are continuous, where  $G \times G$  is equipped with the product topology.

Let  $\mathbf{M}(n, \mathbb{R})$  be the set of all real  $n \times n$  matrices and  $\mathbf{GL}(n, \mathbb{R})$  the subset of all invertible  $n \times n$  matrices. We may identify  $\mathbf{M}(n, \mathbb{R})$  with  $\mathbb{R}^{n^2}$  and  $\mathbf{GL}(n, \mathbb{R})$  as a subset of  $\mathbb{R}^{n^2}$ . We assume  $\mathbf{M}(n, \mathbb{R})$  to be equipped with the Euclidean topology of  $\mathbb{R}^{n^2}$  and  $\mathbf{GL}(n, \mathbb{R})$  to be equipped with the induced subset topology.

- a) Show that  $(\mathbf{M}(n, \mathbb{R}), +)$  is a Lie group.
- b) Show that the determinant  $\det : \mathbf{M}(n, \mathbb{R}) \rightarrow \mathbb{R}$  is a continuous map.
- c) Show that  $(\mathbf{GL}(n, \mathbb{R}), \cdot)$  is a Lie group.

A homomorphism of Lie groups is a continuous group homomorphism.

- d) Is the exponential map  $\exp : \mathbf{M}(n, \mathbb{R}) \rightarrow \mathbf{GL}(n, \mathbb{R})$  a homomorphism of Lie groups?

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### Hints for solution:

- a)  $M(n, \mathbb{R})$  is a topological manifold by G1. Matrix addition is associative, for  $A \in M(n, \mathbb{R})$  we have  $-A \in M(n, \mathbb{R})$  and the zero matrix is also contained in  $M(n, \mathbb{R})$ . Hence,  $M(n, \mathbb{R})$  is a group. Since addition and subtraction of matrices are continuous,  $(M(n, \mathbb{R}), +)$  is a Lie group.
- b) Since  $\det(A)$  is a polynomial in the entries of  $A$  it is continuous.
- c) Since matrix multiplication is associative, the matrices in  $GL(n, \mathbb{R})$  are invertible by choice and the identity is in  $GL(n, \mathbb{R})$ , we have that  $(GL(n, \mathbb{R}), \cdot)$  is a group. Since  $\det$  is continuous by (b) and  $\det^{-1}(\mathbb{R} \setminus \{0\}) = GL(n, \mathbb{R})$ , we have that  $GL(n, \mathbb{R})$  is an open subset of  $M(n, \mathbb{R})$  and hence homeomorphic to  $\mathbb{R}^{n^2}$ . Thus,  $GL(n, \mathbb{R})$  is a topological manifold. Matrix multiplication is continuous since the entries of  $AB$  are polynomials in the entries of  $A$  and  $B$ . The inverse of a matrix  $A$  is given by  $(A_{ij}^{-1}) = (-1)^{i+j} \det(A^{ji}) / \det(A)$ , where  $A^{ji}$  is the matrix  $A$  after deleting the  $j$ -th row and  $i$ -th column. Since the determinant is continuous, we get that the inversion map is continuous. Hence,  $(GL(n, \mathbb{R}), \cdot)$  is a Lie group.
- d) Since  $\exp(A + B) = \exp(A)\exp(B)$  if and only if  $A$  and  $B$  commute,  $\exp$  is not a group homomorphism for  $n > 1$ .

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### Further Exercises

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*These additional exercises are not compulsory.*

#### Exercise F1 (Connected sum)

Let  $M, N$  be two  $n$ -dim. manifolds. The connected sum  $M \# N$  is the manifold formed by deleting a ball inside each manifold and gluing together the resulting boundary spheres, see Figure 1.

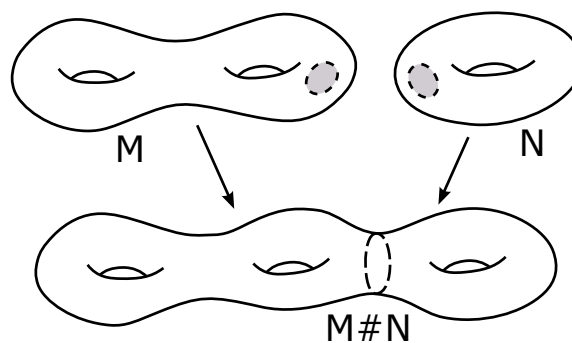


Figure 1: Connected sum  $M \# N$ . ([https://en.wikipedia.org/wiki/Connected\\_sum](https://en.wikipedia.org/wiki/Connected_sum))

We want to show some properties of the connected sum. It suffices to give reasonable arguments. A precise proof is not required.

- a) Show that the connected sum is invariant under homeomorphisms, i.e., if  $M_1 \approx M_2$  and  $N_1 \approx N_2$  then  $M_1 \# N_1 \approx M_2 \# N_2$ .
- b) Show that the connected sum is associative (up to homeomorphisms).
- c) Show that the sphere is the neutral element, i.e.,  $M^n \# \mathbb{S}^n \approx M^n$ .

Let  $S_g := T^2 \# T^2 \# \dots \# T^2$  be the connected sum of  $g$  tori.

- d) Show that  $S_g$  is a connected closed manifold and well-defined up to homeomorphisms.
- e) Show that if  $S_g = S_{g'}$  then  $g = g'$ .

*Remark:* The connected sum is important for the classification of surfaces. In the 1-dimensional case every connected manifold is either homeomorphic to  $\mathbb{R}^1$  or  $\mathbb{S}^1$ . In the 2-dimensional case every connected closed manifold is either homeomorphic to the connected sum of  $g$  tori or the connected sum of  $k$  projective planes. In the first case the surface is orientable and has Euler characteristic  $2 - 2g$ . In the second case the surface is non-orientable and has Euler characteristic  $2 - k$ . To show this statement is not part of this class.

**Exercise F2** (Manifolds not satisfying the "mild topological restrictions")

Find examples of topological spaces which are locally homeomorphic to Euclidean space but not Hausdorff and/or second-countable.

**Hints for solution:**

- Not Hausdorff: line with two origins, see H2
- Not second-countable: disjoint union of uncountably many copies of  $\mathbb{R}$

**Exercise F3** (Connectedness and Path-Connectedness)

Prove that a connected manifold is path-connected.