# Exercise Sheet 2 (Chapters 3 and 4)

# Chapter 3

## Exercise 1. Characterization of orthogonal decompositions

Let  $(V, \varphi)$  be a finite-dimensional vector space equipped with a symmetric bilinear form. Let  $W \subseteq V$  be a subspace.

- (1) Is dim  $W + \dim W^{\perp} \ge \dim V$  always true? Is  $W + W^{\perp} = V$  always true?
- (2) Recall the proof that  $V = W \oplus W^{\perp}$  if and only if  $\varphi_{|W}$  is nondegenerate.

## Exercise 2. Orthogonal subspace to a timelike vector

Prove Proposition 3.8 (copied below) directly, without using the results of § 3.1.

**Proposition.** Let V be a Minkowski space. If  $v \in V$  is timelike, then  $v^{\perp}$  is a spacelike hyperplane, and  $V = \mathbb{R}v \oplus v^{\perp}$ .

### **Exercise 3. Time orientation-preserving criterion**

Let *M* be a matrix in O(n, 1). Show that *f* is time orientation-preserving if and only if the bottom-right coefficient of *M* is positive.

### Exercise 4. Lorentz boosts and structure of the Lorentz group

(1) Show that any element of  $SO^+(1, 1)$  can uniquely be written:

$$\left(\begin{array}{c} \cosh t & \sinh t \\ \sinh t & \cosh t \end{array}\right)$$

with  $t \in \mathbb{R}$ . Show that SO<sup>+</sup>(1, 1) is connected.

(2) An element  $f \in SO^+(n, 1)$  is called a *Lorentz boost* if the set of fixed points of f contains a spacelike subspace of codimension 2. Show that in a suitable basis, a Lorentz boost looks like:

$$\begin{array}{c|c}
I_{n-1} & 0 \\
\hline 0 & \cosh t \sinh t \\ \sinh t \cosh t \\
\end{array}$$

Argue that any Lorentz boost is in the connected component of the identity in O(n, 1).

(3) Show that for any two unit timelike vectors u and v, there exists a unique Lorentz boost f such that f(u) = v.

(4) Show that any matrix  $M \in O^+(n, 1)$  can uniquely be written as M = QB, where B is the matrix of a Lorentz boost and Q is a matrix of the form



with  $Q_1 \in O(n)$ .

(5) Recall why SO(*n*) is connected (optional) and conclude that SO<sup>+</sup>(*n*, 1) is connected.

### Exercise 5. Connected components of the Lorentz group and projective Lorentz group

We recall that the subgroup  $SO^+(n, 1) \subseteq O(n, 1)$  is connected (see Exercise 4).

- (1) Show that  $SO^+(n, 1)$  is the identity component of O(n, 1). Show that it is a normal subgroup. Show that the quotient  $O(n, 1)/SO^+(n, 1)$  is isomorphic to the Klein four-group.
- (2) Show that the center of O(n, 1) is equal to the subgroup of homotheties (scalar multiples of the identity) in O(n, 1), that is,  $Z(O(n, 1)) = \{\pm I_{n+1}\}$ .
- (3) Let  $PO(n, 1) := O(n, 1)/Z(O(n, 1)) = O(n, 1)/\{\pm I_{n+1}\}$  denote the projective Lorentz group. Can you identify it to a subgroup of O(n, 1)?

# Chapter 4

## Exercise 1. Isometries of the hyperboloid

The goal of this exercise is to dermine the group of isometries of hyperbolic space in the hyperboloid model, in particular to provide a careful proof of Theorem 4.7.

Let  $M = \mathbb{R}^{n,1}$  be Minkowski space, denote  $\mathcal{H}$  the hyperboloid of two sheets  $\mathcal{H} = \{v \in M : \langle v, v \rangle = -1\}$ , and  $\mathcal{H}^+$  the upper sheet (with  $x_{n+1} > 0$ .)

- (1) The goal of this question is to show that  $O^+(n, 1)$  acts by isometries on  $\mathcal{H}^+$ .
  - (a) Show that the action of O(n, 1) on *M* leaves  $\mathcal{H}$  invariant.
  - (b) Show that O(n, 1) acts on  $\mathcal{H}$  by Riemannian isometries.
  - (c) Show that  $f \in O(n, 1)$  preserves  $\mathcal{H}^+$  if and only if  $f \in O^+(n, 1)$ . Conclude that  $O^+(n, 1) \subseteq \text{Isom}(\mathcal{H}^+)$ .
  - (d) Optional: Show that  $f \in O^+(n, 1)$  is orientation-preserving on  $\mathcal{H}^+$  if and only if  $f \in SO^+(n, 1)$ . Conclude that  $SO^+(n, 1) \subseteq Isom^+(\mathcal{H}^+)$ .
- (2) The goal of this question is to show that, conversely, any isometry of  $\mathcal{H}^+$  is induced by some element of  $O^+(n, 1)$  acting on M.
  - (a) Show that the action of  $O^+(n, 1)$  on  $\mathcal{H}^+$  is transitive. *Hint: use Exercise 4 (3)*.
  - (b) Derive from the previous question that it is enough to show that any isometry of  $\mathcal{H}^+$  fixing some point is induced by some element of O(n, 1) acting on *M* fixing that point.
  - (c) Identify the subgroup K of O(n, 1) fixing the point  $v_0 = (0, ..., 0, 1)$ . Show that the induced action of K in  $T_{v_0} \mathcal{H}^+$  is transitive on the set of orthonormal bases of  $T_{v_0} \mathcal{H}^+$ .
  - (d) Let f be an isometry of  $\mathcal{H}^+$  fixing  $v_0$ . Show that f is completely determined by its derivative at  $v_0$ .
  - (e) Conclude that  $\text{Isom}(\mathcal{H}^+) = O^+(n, 1)$  and  $\text{Isom}^+(\mathcal{H}^+) = SO^+(n, 1)$ .

### Exercise 2. Distance between geodesics on the hyperboloid

We denote as usual  $\mathcal{H}^+ \subseteq \mathbb{R}^{n,1}$  the upper sheet of the hyperboloid in Minkowski space. Let  $p \in \mathcal{H}^+$ and let  $v, w \in T_p \mathcal{H}^+$  be an orthonormal pair of tangent vectors. It is a general fact of Riemannian geometry that the distance between the geodesics  $\gamma_v(t)$  and  $\gamma_w(t)$  satisfies

$$d(\gamma_{v}(t), \gamma_{w}(t))^{2} = 2t^{2} - \frac{1}{3}K t^{4} + O(t^{5})$$

as  $t \to 0$ , where *K* denotes the sectional curvature of the plane spanned by *v* and *w*. (See § 2.3.3 for more information.)

- (1) Show that  $d(\gamma_v(t), \gamma_w(t)) = \operatorname{arcosh}\left(\cosh^2 t\right)$ .
- (2) Find the Taylor expansion of  $\operatorname{arcosh}(\cosh^2 x)$  to order 3 as  $x \to 0$ .
- (3) Conclude that K = -1.
- (4) Show likewise that  $\mathcal{H}_R^+$  has constant sectional curvature  $-\frac{1}{R^2}$ .

### Exercise 3. Jacobi fields on the hyperboloid

We denote as usual  $\mathcal{H}^+ \subseteq \mathbb{R}^{n,1}$  the upper sheet of the hyperboloid in Minkowski space.

(1) Let  $v, w \in T_p \mathcal{H}^+$  be an orthonormal pair. Let us define  $\gamma \colon \mathbb{R} \times \mathbb{R} \to \mathcal{H}^+$  by

 $\gamma(s,t) = \cosh(t)p + \sinh(t) \left[\cos(s)v + \sin(s)w\right].$ 

Show that:

- (i)  $\gamma(s, \cdot)$  is a unit geodesic for all  $s \in \mathbb{R}$ ,
- (ii)  $\gamma(0, \cdot) = \gamma_v$ .

Such a family  $\gamma$  is called a *variation of geodesics*.

- (2) Let  $J(t) = \frac{\partial}{\partial s}|_{s=0} \gamma(s,t)$ . Check that J(0) = 0 and J'(0) = w. This is a normal Jacobi field.
- (3) We admit the following fact: if J(t) is a normal Jacobi field along a unit geodesic and satisfies J''(t) + k(t)J(t) = 0, then the sectional curvature of the plane spanned by  $\gamma'(t)$  and J(t) is equal to k(t) for all  $t > 0^1$ . Show that the plane spanned by v and w has curvature -1.
- (4) Conclude that  $\mathcal{H}^+$  has constant sectional curvature -1.
- (5) Show similarly that the hyperboloid of radius *R* has constant sectional curvature  $-\frac{1}{R^2}$ .

### Exercise 4. Horocycles on the hyperboloid

Let *P* be an affine plane in Minkowski space  $\mathbb{R}^{2,1}$  whose underlying vector space  $\vec{P}$  is the orthogonal of an isotropic vector *n*. The curve  $\mathcal{H}^+ \cap P$  is called a *horocycle*.

- (1) Show that  $P = \{p \in \mathbb{R}^{2,1} : \langle p, n \rangle = c\}$  where *c* is a constant.
- (2) Optional: Show that any two horocycles are congruent.
- (3) Show that any horocycle is a parabola in  $\mathbb{R}^{2,1}$ .
- (4) (\*) Show that all the geodesics in  $\mathcal{H}^+$  perpendicular to a given horocycle are asymptotic.

<sup>&</sup>lt;sup>1</sup>Students who know Riemannian geometry should recall why this is true. It follows from the Jacobi equation  $J''(t) + R(J(t), \gamma'(t))\gamma'(t) = 0.$ 

# **Exercise 5. Comparing hyperboloids**

We denote  $(\mathcal{H}_R^+, g_R)$  the upper sheet of the hyperboloid of radius R in  $\mathbb{R}^{n,1}$  equipped with its Riemannian metric,

- (1) Find a natural map  $f: \mathcal{H}_R^+ \to \mathcal{H}_1^+$ .
- (2) Compare  $g_R$  and  $f^*g_1$ . Recover the results of § 4.7.

# Exercise 6. Euclid's fifth postulate for the hyperboloid

Does Euclid's fifth postulate hold for the hyperboloid model? Compute the angle of parallelism as a function of the distance a (see Figure 1.3).